

SDL Implementations for Wireless Sensor Networks

Incorporation of PragmaDev's RTDS into the Deterministic Protocol Stack BiPS

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The logo for the Networked Systems Group features a light blue, semi-transparent globe with a grid of latitude and longitude lines. The text "Networked Systems Group" is overlaid on the globe in a bold, black, sans-serif font.

**Networked Systems
Group**



Outline

- 1 Introduction
- 2 BiPS
- 3 Incorporation of SDL into BiPS
 - Scheduling the SDL System
 - Interfacing the SDL Environment
- 4 Evaluation
- 5 Conclusions

Motivation

- ▶ challenges of modern (wireless) sensor systems
 - ▶ efficiency
 - ▶ energy
 - ▶ storage
 - ▶ predictability
 - ▶ communication: Transfer rates, delays, ...
 - ▶ software implementations: Run-time, waiting times
 - ▶ complexity
 - ▶ reuse
 - ▶ determinism
 - ▶ ...

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objective: Find a trade-off combining the benefits of manual and model-driven implementations

Hybrid Design: Model-driven vs. Hand-written

SDL (RTDS)

BiPS

hardware

- ▶ Specification and Description Language (SDL)
 - ▶ language for the specification of distributed systems
 - ▶ tool support for model-driven implementations
- ⇒ *use for applications and higher-layer protocols*

Hybrid Design: Model-driven vs. Hand-written

SDL (RTDS)

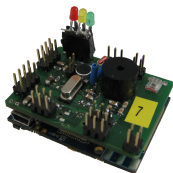
BiPS

hardware

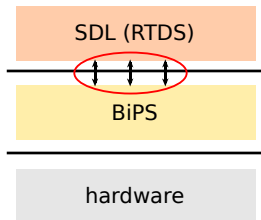
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- ▶ Black burst-integrated Protocol Stack (BiPS)
 - ▶ protocol framework for wireless sensor nodes
 - ▶ operating system functionalities
 - ▶ manual bare implementation for Imote2

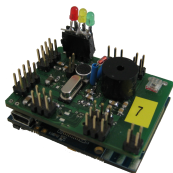
⇒ *use for hardware-related functionality and time-critical (MAC) protocols*



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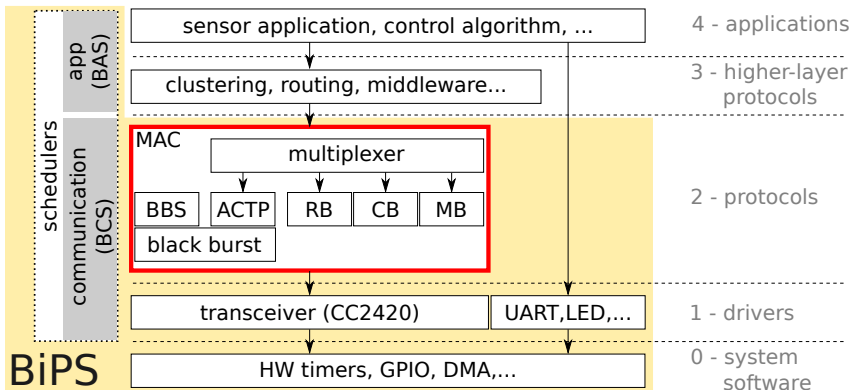
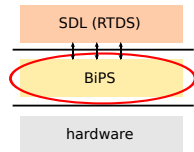
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Black burst-integrated Protocol Stack

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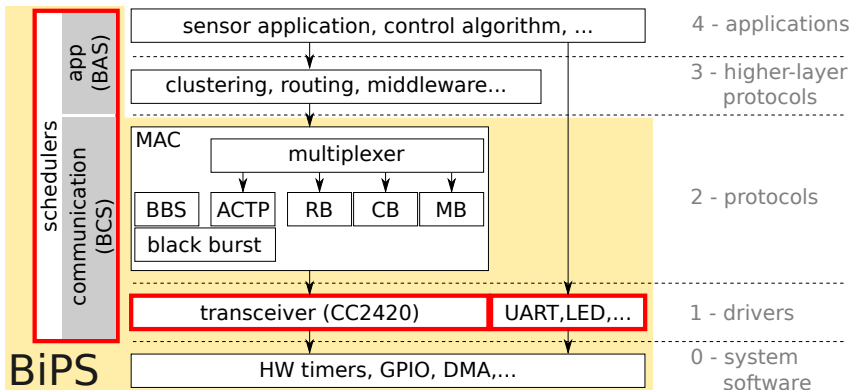
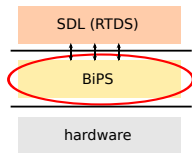
BiPS – (Deterministic) Protocols

- ▶ BBS – Synchronization protocol with bounded offset
- ▶ RB – reservation-based MAC (TDMA)
- ▶ CB – contention-based MAC (CSMA/CA)
- ▶ ...



BiPS – Operating System Functionalities

- ▶ hardware drivers
- ▶ schedulers
 - ▶ BiPS Communication Scheduler (BCS)
 - ▶ BiPS Application Scheduler (BAS)



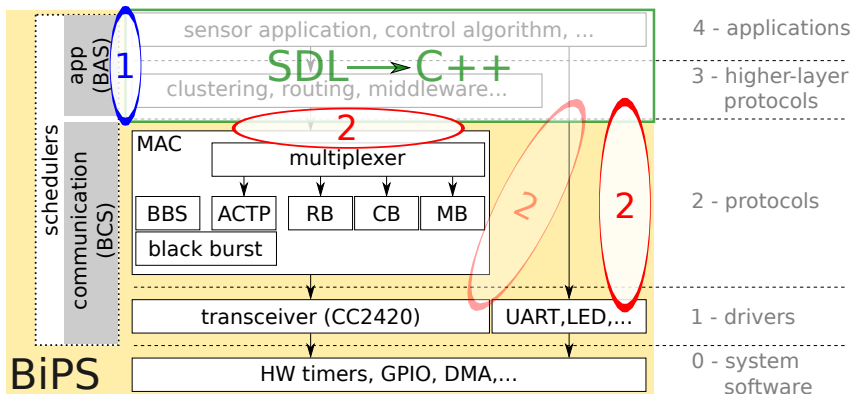
Incorporation of SDL into BiPS

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Incorporation of SDL into BiPS – Integration Steps

► integration steps

1. schedule the SDL system with BAS
2. interface the SDL environment with BiPS



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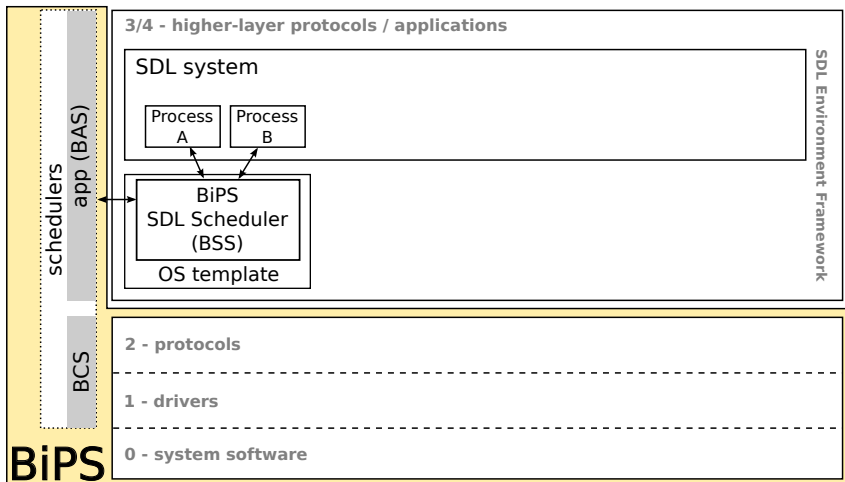
Scheduling the SDL System – Overview

- ▶ tasks of an SDL scheduler
 - ▶ serialize SDL transition executions
 - ▶ deliver SDL signals inter and intra SDL systems
 - ▶ manage SDL timers

Scheduling the SDL System – Overview

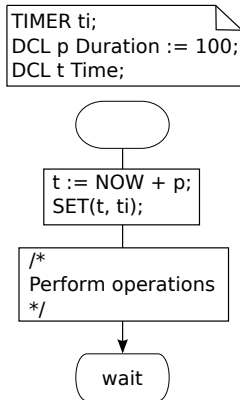
- ▶ tasks of an SDL scheduler
 - ▶ serialize SDL transition executions
 - ▶ deliver SDL signals inter and intra SDL systems
 - ▶ manage SDL timers
- ▶ integration approach
 - ▶ single task scheduling
 - PragmaDev's *rtosless* template
 - ▶ adoption of PragmaDev's CPPScheduler for intra-task scheduling
 - **BiPS SDL Scheduler (BSS)**
 - ▶ signal-based (FIFO)
 - ▶ non-preemptive execution of transitions
 - ▶ scheduling of BSS as application of BAS
 - ▶ SDL system runs with lower priority than BCS
 - ▶ interruptible execution of the SDL system in favor of BiPS protocols

Scheduling the SDL System – BSS in BiPS



Scheduling the SDL System – Comments on BSS

- ▶ realization of SDL time (NOW)
 - ▶ derivation from hardware clock
 - ▶ fine-grained ($1 \mu s$)

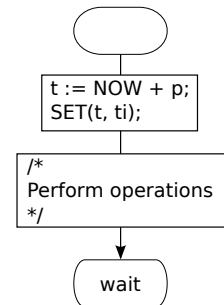


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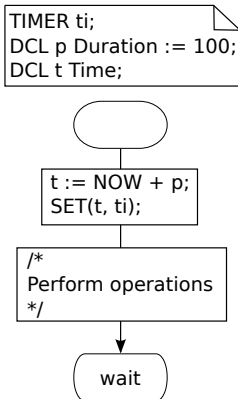
- ▶ incorporation of SDL timers
 - ▶ SDL SET with absolute time values
 - ▶ delegation to timer system of BAS
 - setup of hardware timer
 - ▶ expiration of timer by hardware interrupt
 - execution of BSS after interrupt mode

```
TIMER ti;
DCL p Duration := 100;
DCL t Time;
```

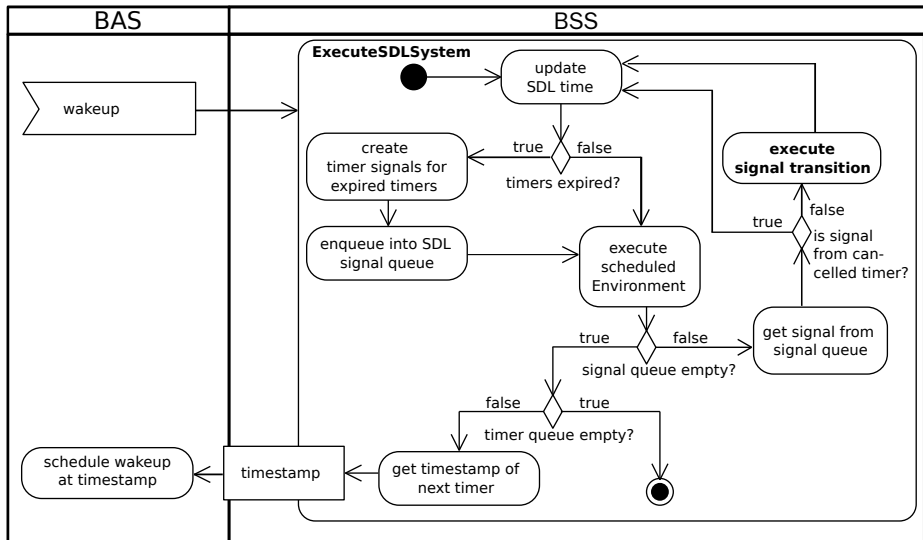


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 - execution of BSS after interrupt mode
- ▶ processing of external events
 - ▶ announced by hardware interrupts
 - ▶ execution of BSS via BAS after interrupt mode



Scheduling the SDL System – Mode of Operation



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Interfacing the SDL Environment – Overview

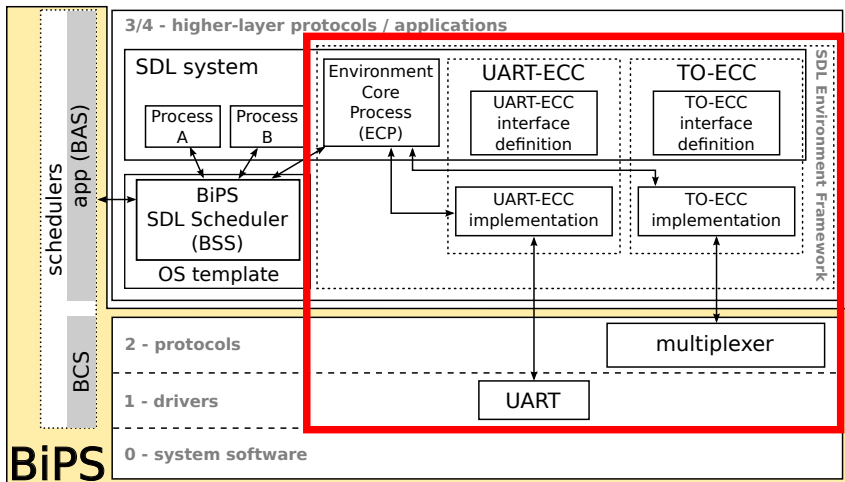
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 - ▶ providing access to hardware peripherals from within SDL systems
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 - ▶ trigger the execution of the system in consequence of external events

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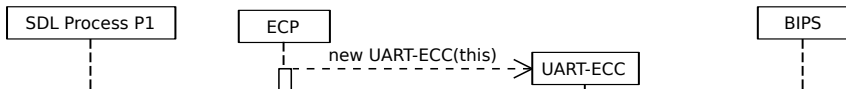
- ▶ tasks of the SDL environment
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- ▶ realization as SDL process → *Environment Core Process* (ECP)
 - ▶ runs under control of BSS
 - ▶ sub-divided into Environment Core Components (ECCs)
 - ▶ access to BiPS functionality (drivers, protocols)
 - ▶ interaction with SDL system via SDL signals
 - ▶ consists of interface definition (SDL package) and implementation (C++)

Interfacing the SDL Environment – Architecture

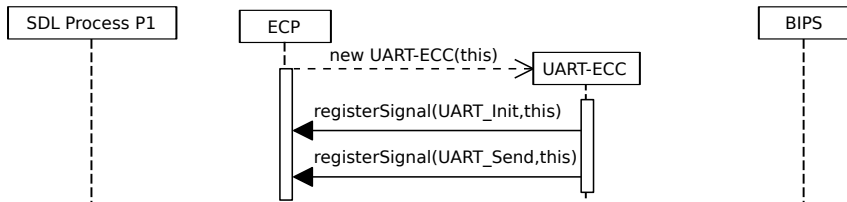


Interfacing the SDL Environment – Initialization of ECCs



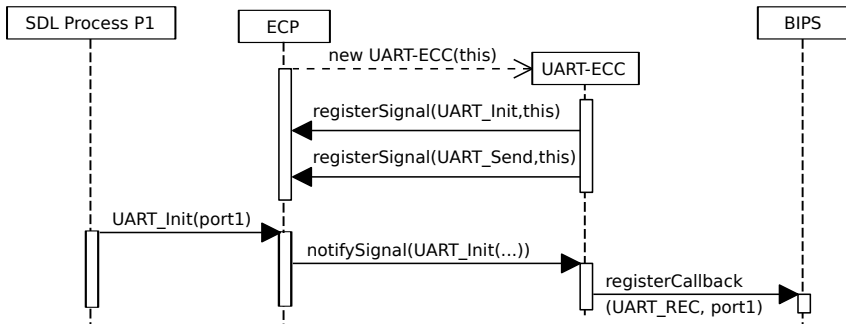
1. ECP creates required ECCs depending on declared SDL signals

Interfacing the SDL Environment – Initialization of ECCs



1. ECP creates required ECCs depending on declared SDL signals
2. ECC registers responsible signals at ECP

Interfacing the SDL Environment – Initialization of ECCs



1. ECP creates required ECCs depending on declared SDL signals
2. ECC registers responsible signals at ECP
3. ECP forwards signal to registered ECC

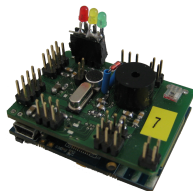
Evaluation

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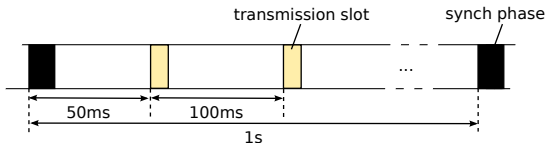
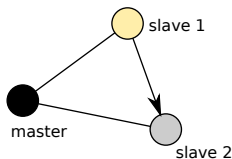
Evaluation – Scenario

► objectives

1. functional evaluation
2. quantification of integration's advantage over pure SDL solution



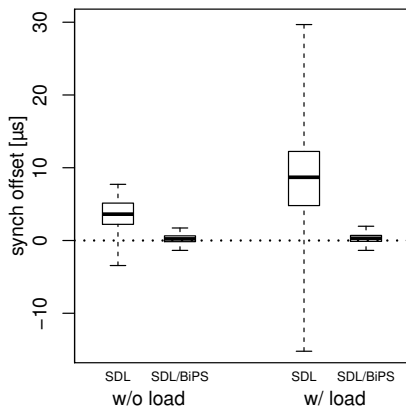
► Scenario



► realizations

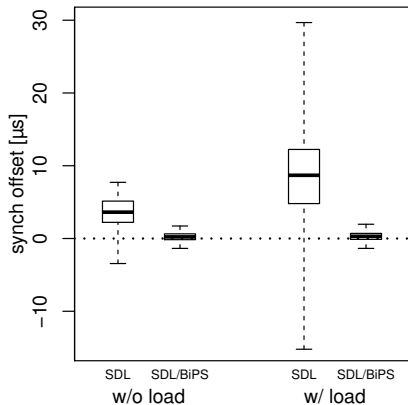
1. **SDL** only (w/o BBS and MAC protocols of BiPS)
2. full **SDL/BiPS** integration

Evaluation – Results

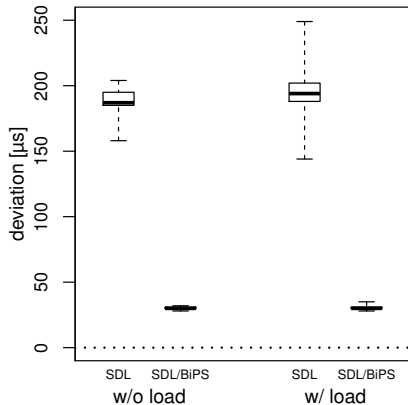


synchronization offset (slaves only)

Evaluation – Results



synchronization offset (slaves only)



temporal deviation of data frames

Conclusions

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- ▶ lessons learned
 1. hybrid approaches have advantages w.r.t. efficiency and predictability
 2. BiPS is an adequate framework and basis for SDL
 3. RTDS provides a flexible interface for new software platforms

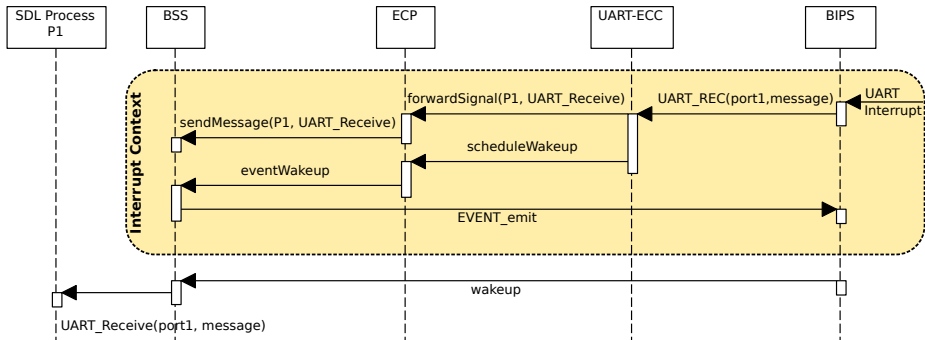
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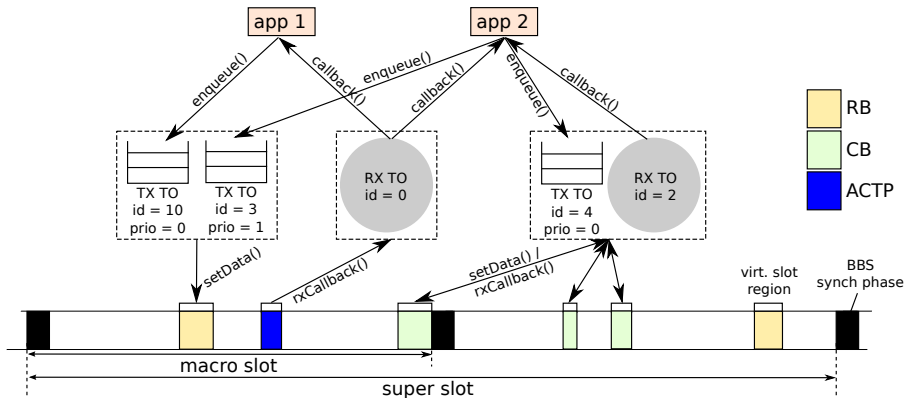
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- ▶ future work
 - ▶ more sophisticated scheduling strategies

SDL Environment – Signals from External Events



BiPS – Multiplexer with Transmission Opportunities (TOs)



SDL Environment: Class Diagram with Observer Pattern

